

# Stability of Polling Systems with State-Independent Routing

Serguei Foss\*, Natalia Chernova<sup>†</sup> and Artyom Kovalevskii<sup>‡</sup>

This paper deals with the stability study of polling systems with either finite or infinite (countable) number of stations (queues) and with a finite number of servers that poll (visit) the stations along some random (state-independent) routes. First, we formulate “global” and “local” stability theorems for systems with a single server and with a general stationary ergodic input. Their proofs are based on certain monotone properties of underlying stochastic processes (see [15-17]). Second, we give a stability criterion for systems with several servers, with a finite number of stations and with i.i.d. driving sequences. The proof of the latter criterion (see [18]) is based on the fluid approximation approach.

Stability conditions for polling systems have undergone study rather recently (see, e.g., [1-12]) and all available papers deal with systems with finitely many stations and (except [2]) with either Poisson or renewal input.

**Keywords:** polling system, stability, stationarity, monotonicity, saturation rule, fluid approximation.

## §1. Systems with a Single Server: “Global” Stability

Our approach is based on ideas of the so-called saturation rule [13].

Introduce a polling system with  $K \leq \infty$  stations. Let  $\langle \Omega, \mathcal{F}, P \rangle$  be a probability space. All random variables below are considered on this space.

**The input.** By the *input* we mean a marked point process  $T$  with points  $T_n$  ( $T_0 = 0$ ) and marks  $\xi_n$ . The sequence  $\xi_n = (\tau_n, \mu_n, \sigma_n)$ ,  $n = 0, \pm 1, \pm 2, \dots$ , is assumed stationary and ergodic. Here  $\tau_n = T_n - T_{n-1}$  is the interarrival time between customer  $(n - 1)$  and customer  $n$ ,  $\mu_n$  is the number of the station to which customer  $n$  is directed, and  $\sigma_n$  is his service time.

Let  $\mathbf{E}\tau_1 = \lambda^{-1}$  be finite and positive;  $\mathbf{E}\sigma_1 = \sigma < \infty$ ; and  $\mathbf{P}(\mu_1 = k) = p_k > 0$  for every  $k = 1, 2, \dots$ ,  $\sum_{k=1}^{\infty} p_k = 1$ .

---

\*ColoState University and Novosibirsk State University, foss@stat.colostate.edu and foss@math.nsc.ru

<sup>†</sup>Novosibirsk State University, root@cher.nsu.ru

<sup>‡</sup>Novosibirsk State University, artyom@math.nsc.ru

**The server route.** Assume to be given a sequence  $\{\nu_j, w_j\}_{j=-\infty}^{\infty}$  of pairs of random variables, where the random variable  $\nu_j$  takes values  $1, \dots, \infty$  and equals the number of the queue visited by the server  $j$ th in succession and the random variable  $w_j \geq 0$  is the walking time from queue  $\nu_j$  to queue  $\nu_{j+1}$ . Suppose that the sequence  $\{\nu_j, w_j\}$  can be partitioned into independent identically distributed (i.i.d.) segments of random length (cycles); i.e., there exists an increasing sequence of integer-valued random variables  $\{j_i\}_{i=-\infty}^{\infty}$  such that the random vectors (“cycles of the route”)

$$\eta_i = (l_i; \nu_{j_i+1}, \dots, \nu_{j_{i+1}}; w_{j_i+1}, \dots, w_{j_{i+1}}), \quad i \in \mathbf{Z},$$

are i.i.d. Here  $l_i = j_{i+1} - j_i$  is the number of queues (stations) visited by the server in cycle  $i$ . Assume that the cycles start with visiting the same queue. For definiteness, let  $\nu_{j_i+1} = 1$  for all  $i$ . Denote by  $c_k^i = I(\nu_{j_i+1} = k) + \dots + I(\nu_{j_{i+1}} = k)$  the number of visits to queue  $k$  in cycle  $i$ , where  $\mathbf{P}(c_k^1 > 0) > 0$  for all  $k$ , and denote by  $\psi_i = w_{j_i+1} + \dots + w_{j_{i+1}}$  the total walking time during the cycle.

Let  $L = \mathbf{E}l_1 < \infty$ ,  $W = \mathbf{E}\psi_1 < \infty$ , and  $C_k = \mathbf{E}c_k^1 < \infty$  for all  $k$ . Assume the sequences  $\{\eta_i\}$  and  $\{\xi_n\}$  to be independent.

By a *route of the server in the empty system* we mean a marked point random process whose points are the starting times of the cycles and the distance between points equals the total walking time during the corresponding cycle.

Denote by  $\Psi = \{\Psi_i, \eta_i\}$  the point process with points  $\Psi_i$  and marks  $\eta_i$ ,  $i \in \mathbf{Z}$ , in which  $\Psi_0 = 0$  and  $\Psi_i = \Psi_{i-1} + \psi_i$  is the finish time of cycle  $i$  if the server moves in the empty system.

Consider also a stationary version (in continuous time) of the process  $\Psi$  which we denote by  $\Psi^{(1)} = (\Psi_i^{(1)}, \eta_i^{(1)})_{i=-\infty}^{\infty}$ . Assign the number 0 to the first positive point of this process, so that  $\Psi_0^{(1)} > 0 \geq \Psi_{-1}^{(1)}$  a.s.

Denote by  $\Psi^{(-n)}$ ,  $n \geq 0$ , the stationary ergodic point process that is obtained from the process  $\Psi^{(1)}$  by shifting each point to the left by the random variable  $\sum_{j=-n}^0 \sigma_j$  and is renumbered so that  $\Psi_0^{(-n)}$  is its first positive point.

Since  $\Psi^{(1)}$  and  $\{\xi_k\}_{k=-\infty}^{\infty}$  are independent, for every  $n \geq -1$  the process  $\Psi^{(-n)}$  is independent of the sequence  $\{\xi_k\}_{k=-\infty}^{\infty}$  and its distribution coincides with the distribution of  $\Psi^{(1)}$ .

**The service policies.** If the server, on visiting station  $k$  at time  $j$ , finds  $x$  customers in a queue, then it serves, without interruption,  $f_k^j(x) \equiv f_k(x, D_k^j) \leq x$  customers in the *FIFO* order, and then moves to the next station of the route. Upon service completion, customers leave the system. Here (for every  $k$ ) the random variables  $D_k^j$ ,  $j = 0, \pm 1, \pm 2, \dots$ , are i.i.d. Suppose that the service policies satisfy the conditions  $\mathbf{P}(f_k^j(1) = 1) = \delta_k > 0$  and  $f_k^j(x) \leq x$  a.s. for all  $x \in \mathbf{Z}^+$ ,  $k = 1, \dots, K$ , and belong to the class  $M = \{f : f(x, y) \leq f(x+1, y) \leq f(x, y) + 1 \text{ for all } x \in \mathbf{Z}^+, y \in \mathbf{R}\}$ . We call the class  $M$  the *class of monotone service policies*. For the service policies in  $M$ , there always exists a (finite or infinite) limit

$$F_k = \mathbf{E} \lim_{x \rightarrow \infty} f_k(x, D_k^j) = \mathbf{E}F_k(D_k^j) \leq \infty.$$

Henceforth the number  $[m, n]$  and the arguments  $\Psi$  and  $T = \{T_k\}$  in some characteristic of the system (queue length, exhaustion time, etc.) signify that the characteristic is

considered in the system that is governed by the route  $\Psi$  of the server and to which only the customers with numbers  $m \leq \dots \leq n$  are submitted at respective times  $T_m \leq \dots \leq T_n$ . By a *nonempty* cycle we mean a cycle during which there are customers in the system.

Denote by  $X_{[m,n]} = X_{[m,n]}(T, \Psi)$  and  $\widetilde{X}_{[-k,l]} = X_{[-k,l]}(T, \Psi^{(-k)})$  the finish times of the last nonempty cycles in the corresponding systems.

Given two systems of the above-described type with (possibly) different arrival times of customers and the service policies, we shall write  $T \leq T'$  a.s., provided that  $T_n \leq T'_n$  a.s. for all  $n$ , and write  $f \geq f'$  a.s., provided that  $f_k^j(x) \geq f'^j_k(x)$  a.s. for all  $k = 1, 2, \dots$ ,  $j = 1, 2, \dots$ ;  $x \in \mathbf{Z}^+$ .

The above objects enjoy the *monotonicity property*:

If  $T \leq T'$  and  $f \geq f'$  a.s. then

$$X_{[m,n]}(T) \leq X_{[m,n]}(T'), \quad \widetilde{X}_{[-k,l]}(T) \leq \widetilde{X}_{[-k,l]}(T').$$

Introduce the following notations:

$$Z_{[m,n]}(T) = X_{[m,n]}(T) - T_n, \quad \widetilde{Z}_{[-n,m]}(T) = \widetilde{X}_{[-n,m]}(T) - T_m,$$

$$X_1(T) = X_{[1,1]}(T), \quad Z_1(T) = Z_{[1,1]}(T).$$

Assume the following condition to be satisfied:

(A<sub>1</sub>)  $\mathbf{E}X_1(T) < \infty$ .

The condition (A<sub>1</sub>) is always valid for systems with finite number of stations.

Under condition (A<sub>1</sub>), we have

**Lemma 1** (Law of Large Numbers). There exists a finite constant  $\gamma \geq 0$  such that

$$\frac{Z_{[1,n]}}{n} \xrightarrow{\mathbf{P}} \gamma, \quad \lim_{n \rightarrow \infty} \frac{\mathbf{E}Z_{[1,n]}}{n} = \gamma;$$

$$\frac{Z_{[-n,-1]}}{n} \xrightarrow{\mathbf{P}} \gamma, \quad \lim_{n \rightarrow \infty} \frac{\mathbf{E}Z_{[-n,-1]}}{n} = \gamma.$$

Given an arbitrary  $0 \leq c < \infty$ , denote by  $cT$  the process that consists of the points  $\{cT_i\}$ ,  $i \in \mathbf{Z}$ , and the marks  $(c\tau_i, \mu_i, \sigma_i)$ . The monotonicity property and (A<sub>1</sub>) imply

**Lemma 2** . For every  $c \geq 0$ , there exists a nonnegative constant  $\gamma(c)$  such that

$$\frac{Z_{[1,n]}(cT)}{n} \xrightarrow{\mathbf{P}} \gamma(c);$$

moreover,  $\gamma(c)$  decreases in  $c$ , whereas  $\gamma(c) + c\lambda^{-1}$  increases in  $c$ .

Denote

$$\gamma(0) = \lim_{c \searrow 0} \gamma(c) = \lim_n \frac{Z_{[1,n]}(0 \cdot T)}{n}.$$

- Theorem 1** . 1.  $\gamma(0) = \sigma + \sup_k \frac{p_k}{F_k C_k} W$ .
2. There exists  $\lim_n \widetilde{X}_{[-n,0]}$  in the sense of convergence a.s.
3. The event  $\{\lim_n \widetilde{X}_{[-n,0]} < \infty\}$  has probability 0 or 1.
4. Let condition  $(A_1)$  hold. If  $\lim \widetilde{X}_{[-n,0]}(T) = \infty$  a.s. then  $\rho \equiv \lambda\gamma(0) \geq 1$ . If  $\rho > 1$  then  $\lim \widetilde{X}_{[-n,0]}(T) = \infty$  a.s.

For the system governed by the process  $\Psi^{(-n)}$ , let  $Q_{[-n,m]}^k(t)$  stand for the queue length at station  $k$  at time  $t$ ;  $\chi_{[-n,m]}^k(t)$ , the residual service time at station  $k$  at time  $t$ ;  $\chi_{[-n,m]}^0(t)$ , the residual interarrival time;  $\eta_{[-n,m]}(t)$ , the cycle of the route in which the server is at time  $t$  (the random vector composed of the numbers of stations and the walking times between them); and  $\varphi_{[-n,m]}(t)$ , the residual (total) walking time of the server in the cycle  $\eta_{[-n,m]}(t)$ .

Set the corresponding quantities equal to zero if their values at time  $t$  are not defined. All above characteristics are assumed right continuous. Put

$$Y_{[-n,m]} = \{\{Q_{[-n,m]}^k(t)\}_{k=1}^\infty, \{\chi_{[-n,m]}^k(t)\}_{k=0}^\infty, \eta_{[-n,m]}(t), \varphi_{[-n,m]}(t), 0 \leq t \leq T_m\}.$$

Given random variables  $X$  and  $Y$  on the probability space  $\langle \Omega, \mathcal{F}, P \rangle$ , we call  $X$  a *copy* of  $Y$  if there exists a one-to-one measure-preserving  $\mathcal{F}$ -measurable shift transformation  $\theta$  on  $\Omega$  such that  $X(\omega) = Y(\theta\omega)$  for all  $\omega$ .

We say that the process  $\check{X}(t)$  is *Palm-stationary* (with respect to the nested times  $\{T_n\}$ , where  $T_0 = 0$ ) if for every  $n$  the process  $\{\check{X}^n(t) = \check{X}(t + T_n), t \geq 0\}$  is a copy of the process  $\{\check{X}(t), t \geq 0\}$ .

For the process  $\{\check{X}(t), \infty \leq t \leq \infty\}$  and for any  $m = 1, 2, \dots$ , put  $\check{Y}^m = \{\check{X}(t), 0 \leq t \leq T_m\}$ .

Denote by  $Q_n^k = Q_{[1,n]}^k(T_n)$  the queue length at station  $k$  at time  $T_n$  in the polling system governed by the process  $\Psi$ , set  $\vec{Q}_n = \{Q_n^k; k = 1, 2, \dots\}$ . Let  $Q_n = \sum_{k=1}^\infty Q_n^k$  stand for the total queue length.

**Theorem 2** . Assume that condition  $(A_1)$  holds.

1. If  $\rho < 1$  then, on the probability space  $\langle \Omega, \mathcal{F}, P \rangle$ , there exists a *Palm-stationary* process  $\{\check{X}(t), \infty \leq t \leq \infty\}$  such that for every  $m = 1, 2, \dots$  there is a sequence  $\{\check{Y}^{n,m}\}_{n=1}^\infty$  of copies of the process  $\check{Y}^m$  for which

$$\mathbf{P}(Y_{[-n,m]} \neq \check{Y}^{n,m}) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

In particular, there exists a stationary sequence  $\{\vec{Q}^{(n)}; \infty < n < \infty\}$  such that

$$\mathbf{P}(\vec{Q}_n = \vec{Q}^{(n)}) \rightarrow 1$$

as  $n \rightarrow \infty$ .

2. If  $\rho > 1$  then there exists  $k < \infty$  such that  $\sum_{j=1}^k Q_n^j \rightarrow \infty$  a.s. as  $n \rightarrow \infty$ .

**Remark 1.** It is noteworthy that the existence of the Palm version of a stationary process implies the existence of a stationary process in continuous time (and vice

versa) and some formulas are known that connect the distributions of these marked point processes (see, for instance, [14]).

**Remark 2.** Extend the class of the service policies under consideration as follows: Let  $\widehat{B} = \{f : \text{for every } y \text{ there is } \lim_{x \rightarrow \infty} f(x, y) = F(y) \leq \infty\}$  and  $B = \{f : \text{for every } y \text{ there is } \lim_{x \rightarrow \infty} f(x, y) = F(y) \leq \infty, f(x, y) \leq F(y) \text{ for all } y \in \mathbf{R}, x \in \mathbf{Z}^+\}$ .

It is easy to see that  $M \subset B \subset \widehat{B}$ . For the service policies in the class  $\widehat{B}$ , there exists

$$F_k = \mathbf{E} \lim_{x \rightarrow \infty} f_k(x, D_k^j) = \mathbf{E} F_k(D_k^j) \leq \infty.$$

**Theorem 3** Consider a system with service policies in the class  $\widehat{B}$ . If  $\rho < 1$  then  $Q_n$  is bounded in probability; i.e.,

$$\lim_{x \rightarrow \infty} \sup_n \mathbf{P}(Q_n > x) = 0.$$

**Theorem 4** Consider a system with policies in the class  $B$ . If  $\rho > 1$  then there exists  $k < \infty$  such that  $\sum_{j=1}^k Q_n^j \xrightarrow{P} \infty$  as  $n \rightarrow \infty$ .

The claim of Theorem 4 fails (in general) for systems with policies in the class  $\widehat{B}$ .

## §2. Systems with a Single Server: “Local” Stability

Consider a model with  $K < \infty$  stations. Assume that  $\rho > 1$ , i.e. the “global” system is unstable. The problem is: do some stable station still exist? We give a positive answer on this question, but under slightly more restrictive assumptions on distributions of driving sequences.

Assume that service time at each station  $k$  form a stationary ergodic sequence  $\{\sigma_n(k)\}$  with finite mean  $\sigma(k)$ , all these sequences are mutually independent and do not depend on the sequence  $\{(\tau_n, \mu_n)\}$ . Put  $a_k = \frac{p_k}{F_k C_k} \geq 0$  and permit stations in such an order that

$$a_1 \leq a_2 \leq \dots \leq a_K.$$

For  $k = 1, \dots, K$ , set

$$\rho_k = \lambda \left( \sum_{j=1}^k \sigma(j) p_j + a_k (W + \sum_{j=k+1}^K \sigma_j p_j F_j C_j) \right)$$

(here  $0 \times \infty = 0$ ). Note that  $\rho_k \leq \rho_{k+1}$  for all  $k$ , and  $\rho_K = \rho$ .

**Theorem 5** If  $\rho_k < 1$  for some  $k = 1, \dots, K$ , then there exists a stationary  $k$ -dimensional sequence  $\{\vec{Q}^{(n)}(k)\}$  such that

$$\mathbf{P}((Q_n^1, \dots, Q_n^k) = \vec{Q}^{(n)}(k)) \rightarrow 1$$

as  $n \rightarrow \infty$ .

Under assumption  $(A_1)$ , a similar result takes place for systems with infinite number of stations. One can formulate natural analogs of Theorem 1-4 also.

### §3. Systems with Finite Number of Stations and with Several Servers

Consider a model with  $K < \infty$  stations. Assume that interarrival times  $\{\tau_n\}$  form an i.i.d. sequence with mean  $\lambda^{-1}$ , each customer (independently of everything else) is sent to station  $k = 1, \dots, K$  with probability  $p_k$ . Each server has its own regenerative routing mechanism and service policies. All service policies are assumed to be limited:  $F_k^{(m)} < \infty$  for any server  $m$  and for any station  $k$ . Within one cycle, a server  $m$  visits any station  $k$  a random number of times with finite mean  $C_k^{(m)}$ , and its mean cycle walking time is  $W^{(m)}$ .

**Theorem 6** *Assume interarrival times to have an unbounded distribution. Then the model is stable if and only if  $\tilde{\rho} < 1$ .*

The “unboundedness” assumption may be weakened variously. Here  $\tilde{\rho} = \lambda \sum_{r=1}^R \beta^{(r)}$ , and  $R$  and  $\beta^{(r)}$ ,  $r = 1, \dots, R$  are defined by the following recursive procedure.

For  $1 \leq i, j \leq K$ ,  $1 \leq m \leq M$ , put

$$\varphi_{i,j} = \sum_{m=1}^M \frac{F_i^{(m)} C_i^{(m)}}{W^{(m)} + \sum_{k=1}^j \sigma_k^{(j)} F_k^{(j)} C_k^{(j)}}.$$

Set

$$p_i^{(1)} = p_i; \varphi_1^{(i)} = \varphi_{i,K}; \alpha_i^{(1)} = \frac{p_i^{(1)}}{\varphi_i^{(1)}}; \beta^{(1)} = \min_{1 \leq i \leq K} \alpha_i^{(1)}.$$

Take  $K(1) = K$ . Assume that, for some  $k \geq 1$ , we have previously defined  $K(1) > K(2) > \dots > K(r) \geq 1$  and, for  $1 \leq k \leq r$ ,  $1 \leq i \leq K(k)$ , we know the values of  $p_i^{(k)}$ ,  $\varphi_i^{(k)}$ ,  $\alpha_i^{(k)}$  and  $\beta^{(k)} = \min_i \alpha_i^{(k)}$ .

Permit a sequence  $\{1, 2, \dots, K(r)\}$  in such a way that (after permutation)

$$\alpha_1^{(r)} \geq \alpha_2^{(r)} \geq \dots \geq \alpha_{K(r)}^{(r)}.$$

If  $\alpha_1^{(r)} = \alpha_{K(r)}^{(r)}$ , then stop with the procedure and put  $R = r$ . Otherwise, set

$$K(r+1) = \max\{l : \alpha_l^{(r)} > \alpha_{l+1}^{(r)}\}$$

and, for any  $1 \leq i \leq K(r+1)$ , put

$$p_i^{(r+1)} = \varphi_i^{(r)} (\alpha_i^{(r)} - \alpha_{K(r)}^{(r)}); \varphi_i^{(r+1)} = \varphi_{i,K(r+1)};$$

$$\alpha_i^{(r+1)} = \frac{p_i^{(r+1)}}{\varphi_i^{(r+1)}}; \beta^{(r+1)} = \min_i \alpha_i^{(r+1)}.$$

## References

- [1] H. Lévy, M. Sidi, and O. J. Boxma, “Dominance relations in polling systems,” *Queueing Systems*, **6**, 155–171 (1990).
- [2] L. Massoulié, “Stability of nonmarkovian polling systems,” in: Abstracts: Proc. Conf. Appl. Probab., Paris, 1993. (Submitted to *Queueing Systems*.)
- [3] A. A. Borovkov and R. Schassberger, “Ergodicity of a polling network,” *Stochastic Process Appl.*, **50**, 253–262 (1994).
- [4] S. Foss and G. Last, “On the stability of greedy polling systems with exhaustive service policies,” in: Technical Report 18/94, Technical University Braunschweig, 1994. (To appear in *Ann. Appl. Probab.*)
- [5] S. Foss and G. Last, “On the stability of greedy polling systems with general service policies,” in: Technical Report 6/95, Technical University Braunschweig, 1995.
- [6] C. Fricker and M. R. Jaibi, “Monotonicity and stability of periodic polling models,” *Queueing Systems*, **15**, 211–238 (1994).
- [7] L. Georgiadis and W. Szpankowski, “Stability of token passing rings,” *Queueing Systems*, **11**, 7–34 (1992).
- [8] D. P. Kroese and V. Schmidt, “A continuous polling system with general service times,” *Ann. Appl. Probab.*, **2**, 906–927 (1992).
- [9] D. P. Kroese and V. Schmidt, “Single-server queues with spatially distributed arrivals,” *Queueing Systems*, **17**, 317–345 (1994).
- [10] R. Schassberger, “Stability of polling networks with state-dependent server routing,” in: Technical Report 12/93, Technical University Braunschweig, 1993.
- [11] V. Sharma, “Stability and continuity of polling systems,” *Queueing Systems*, **16**, 115–137 (1994).
- [12] H. Takagi, *Queueing Analysis of Polling Systems* in: *Stochastic Analysis of Computer and Communications System*, Hideaki Takagi (ed.), Elsevier Science Pub. North-Holland (1990).
- [13] F. Baccelli and S. Foss, “On the saturation rule for the stability of queues,” *J. Appl. Probab.*, **32**, No. 2, 494–507 (1995).
- [14] F. Baccelli and P. Bremaud, *Elements of Queueing Theory*, Springer, Berlin (1994).
- [15] S. Foss and N. Chernova, “Comparison theorems and ergodic properties of polling systems,” Preprint No. 6, Institute of Mathematics, Novosibirsk (1995) - to appear in *Problems of Information Transmission* (1996).

- [16] S. Foss and N. Chernova, “On polling systems with infinitely many stations,” *Siberian Math. J.*, **37**, 940-956 (1996).
- [17] S. Foss and N. Chernova, “On a local stability in polling models” (in preparation).
- [18] A. Kovalevskii and S. Foss, “Stability of polling models with many servers” (in preparation).